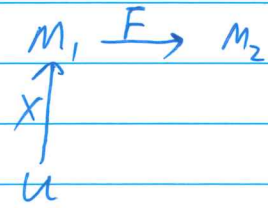


Assignment 3

① Let $X: U \subseteq \mathbb{R}^2 \rightarrow M_1$ be any parametrization of M_1 around p and $X(u_0, v_0) = p$.

For any $\vec{v} = aX_u + bX_v \in T_p M_1$, let $\alpha(t)$ be a smooth curve on M_1 , such that $\alpha(0) = p$, $\alpha'(0) = \vec{v}$.



Let $\beta(t) = X^{-1} \circ \alpha(t)$ be a smooth curve on $U \subseteq \mathbb{R}^2$, then

$$\alpha(t) = X \circ X^{-1} \circ \alpha(t) = X \circ \beta(t)$$

$$\alpha'(0) = [X_u, X_v] \cdot \vec{\beta}'(0)^T$$

\therefore we have $\vec{\beta}'(0) = (a, b)$ since $\alpha'(0) = aX_u + bX_v$.

By definition,

$$dF_p(\vec{v}) = \left. \frac{d}{dt} F(\alpha(t)) \right|_{t=0}$$

$$= \left. \frac{d}{dt} (F \circ X)(X^{-1} \circ \alpha) \right|_{t=0} \quad \text{where } F \circ X: U \subseteq \mathbb{R}^2 \rightarrow M_2 \subseteq \mathbb{R}^3 \text{ is a smooth map.}$$

$$= D(F \circ X) \cdot \vec{\beta}'(0)$$

$$= D_u(F \circ X) \cdot a + D_v(F \circ X) \cdot b$$

$\therefore dF_p$ does not depend on the choice of $\alpha(t)$.

$\therefore dF_p: T_p M_1 \rightarrow T_q M_2$ is well-defined.

• For any $v_1 = aX_u + bX_v$, $v_2 = cX_u + dX_v$

$$dF_p(v_1 + v_2) = dF_p((a+c)X_u + (b+d)X_v)$$

$$= D_u(F \circ X) \cdot (a+c) + D_v(F \circ X) \cdot (b+d)$$

$$= [D_u(F \circ X) \cdot a + D_v(F \circ X) \cdot b] + [D_u(F \circ X) \cdot c + D_v(F \circ X) \cdot d]$$

$$= dF_p(v_1) + dF_p(v_2)$$

$\therefore dF_p$ is linear.

② $X(u, v) = (\phi(v) \cos u, \phi(v) \sin u, \psi(v))$ where $[\phi'(v)]^2 + [\psi'(v)]^2 = 1$
 since v is the arc-length of α .

$\therefore X_u = (-\phi \sin u, \phi \cos u, 0)$

$X_v = (\phi' \cos u, \phi' \sin u, \psi')$

$\therefore N = \frac{X_u \times X_v}{|X_u \times X_v|} = \frac{(\phi \psi' \cos u, \phi \psi' \sin u, -\phi \phi')}{|(\phi \psi' \cos u, \phi \psi' \sin u, -\phi \phi')|}$ $\phi(v) \neq 0$, otherwise $X_u = 0$.
 $= \frac{(\psi' \cos u, \psi' \sin u, -\phi')}{\sqrt{(\phi')^2 + (\psi')^2}} = (\psi' \cos u, \psi' \sin u, -\phi')$

$X_{uu} = (-\phi \cos u, -\phi \sin u, 0)$

$X_{uv} = (-\phi' \sin u, \phi' \cos u, 0)$

$X_{vv} = (\phi'' \cos u, \phi'' \sin u, \psi'')$

$\therefore g_{ij} = \begin{bmatrix} \phi^2 & 0 \\ 0 & (\phi')^2 + (\psi')^2 \end{bmatrix} = \begin{bmatrix} \phi^2 & 0 \\ 0 & 1 \end{bmatrix}$

$h_{ij} = \begin{bmatrix} -\phi \psi' & 0 \\ 0 & \phi'' \psi' - \phi' \psi'' \end{bmatrix}$

\therefore the curvatures are

$$K = \frac{\det(h)}{\det(g)} = \frac{\phi \phi' \psi' \psi'' - \phi \phi'' (\psi')^2}{\phi^2}$$

$$= \frac{\phi \phi' (-\phi' \psi'') - \phi \phi'' [1 - (\phi')^2]}{\phi^2}$$

$$= \frac{-\phi (\phi')^2 \psi'' - \phi \phi'' + \phi (\phi')^2 \phi'}{\phi^2}$$

$$= -\frac{\phi''}{\phi}$$

$$H = \text{tr}(g^{ij} h_{ij}) = -\frac{\phi \psi'}{\phi^2} + \phi'' \psi' - \phi' \psi''$$

$$= \frac{\phi \phi' \psi' - \psi' - \phi \phi' \psi''}{\phi}$$

③ The equation of the surface is

$$X(t, s) = (\sin t \cdot \cos s, \sin t \cdot \sin s, \cos t + g \tan^2 \frac{t}{2})$$

$$\bullet X_t = (\cos t \cdot \cos s, \cos t \cdot \sin s, -\sin t + \frac{1}{\sin t})$$

$$X_s = (-\sin t \cdot \sin s, \sin t \cdot \cos s, 0)$$

$$\bullet N = \frac{X_t \times X_s}{|X_t \times X_s|} = (-\cos t \cdot \cos s, -\cos t \cdot \sin s, \sin t)$$

$$\bullet X_{tt} = (-\sin t \cdot \cos s, -\sin t \cdot \sin s, -\cos t - \frac{\cos t}{\sin^2 t})$$

$$X_{ts} = (-\cos t \cdot \sin s, \cos t \cdot \cos s, 0)$$

$$X_{ss} = (-\sin t \cdot \cos s, -\sin t \cdot \sin s, 0)$$

$$\bullet g = \begin{bmatrix} \frac{\cos^2 t}{\sin^2 t} & 0 \\ 0 & \sin^2 t \end{bmatrix}$$

$$\bullet h = \begin{bmatrix} -\frac{\cos t}{\sin t} & 0 \\ 0 & \sin t \cdot \cos t \end{bmatrix}$$

The Gaussian curvature is

$$K = \frac{\det(h)}{\det(g)} = \frac{-\cos^2 t}{\cos^2 t} = -1$$

④ $\bullet X_x = (1, 0, 2x), X_y = (0, 1, 2ky)$

$\therefore T_p M = \text{span}\{(1, 0, 0), (0, 1, 0)\}$ when $P = (0, 0, 0)$

$\bullet X_{xx} = (0, 0, 2), X_{xy} = (0, 0, 0), X_{yy} = (0, 0, 2k)$

$\therefore N(P) = (0, 0, 1)$

$\therefore g_p = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, h_p = \begin{bmatrix} 2 & 0 \\ 0 & 2k \end{bmatrix}$

$\therefore S_p = g^{-1} \cdot h = \begin{bmatrix} 2 & 0 \\ 0 & 2k \end{bmatrix}$

$\therefore S_p(e_1) = 2e_1, S_p(e_2) = 2k \cdot e_2$

the principal curvatures of M at P are
2, 2k

⑤ Let α be a smooth curve on M parametrized by arc-length such that $\alpha(0) = p$, $\alpha'(0) = \vec{v} = \cos\theta \cdot e_1 + \sin\theta \cdot e_2$

$$\begin{aligned} \therefore k_n &= \langle \alpha''(t), N(\alpha(t)) \rangle \\ &= -\langle \alpha'(t), \frac{d}{dt} N(\alpha(t)) \rangle \quad \text{since } \alpha'(t) \in TM \\ &= \langle \alpha'(t), S_p(\alpha'(t)) \rangle \end{aligned}$$

$$\begin{aligned} \therefore k_n(p) &= \langle \alpha'(0), S_p(\alpha'(0)) \rangle \\ &= \langle \cos\theta \cdot e_1 + \sin\theta \cdot e_2, \cos\theta \cdot k_1 \cdot e_1 + \sin\theta \cdot k_2 \cdot e_2 \rangle \\ &= k_1 \cos^2\theta + k_2 \sin^2\theta. \end{aligned}$$

⑥ (i) • Let $\{v_1, v_2\}$ be an orthonormal basis of $T_p(M)$ with $v_1 \times v_2 = N$

$$\left[\begin{array}{l} \text{claim: the Gaussian curvature is given by} \\ K = \langle \partial_{v_1} N \times \partial_{v_2} N, N \rangle \end{array} \right]$$

Let $X: U \rightarrow M$ be any parametrization of M around p such that

$$N = \frac{\partial_u X \times \partial_v X}{|\partial_u X \times \partial_v X|}$$

Let g, h be the respective first and second fundamental forms.

$$\text{Then } \begin{bmatrix} S_p(X_u) \\ S_p(X_v) \end{bmatrix} = g^{-1} \cdot h \begin{bmatrix} X_u \\ X_v \end{bmatrix}$$

$$\text{and } K = \det(g^{-1} \cdot h)$$

$$\text{let } \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} X_u \\ X_v \end{bmatrix} \text{ for some real numbers } a, b, c, d$$

$$\text{then } \begin{bmatrix} \partial_{v_1} N \\ \partial_{v_2} N \end{bmatrix} = \begin{bmatrix} -S_p(v_1) \\ -S_p(v_2) \end{bmatrix} = - \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} S_p(X_u) \\ S_p(X_v) \end{bmatrix} = - \begin{bmatrix} a & b \\ c & d \end{bmatrix} g^{-1} \cdot h \begin{bmatrix} X_u \\ X_v \end{bmatrix}$$

$$\begin{aligned} \therefore \partial_{v_1} N \times \partial_{v_2} N &= (ad-bc) \cdot \det(g^{-1} \cdot h) \cdot X_u \times X_v \\ &= (ad-bc) \cdot K \cdot \frac{1}{ad-bc} v_1 \times v_2 \quad \text{since } \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} X_u \\ X_v \end{bmatrix} \\ &= K \cdot v_1 \times v_2 \\ &= K \cdot N \end{aligned}$$

$$\therefore K = \langle K \cdot N, N \rangle = \langle \partial_{v_1} N \times \partial_{v_2} N, N \rangle$$

$$\bullet \therefore d(fN)(\vec{v}) = \partial_{\vec{v}} f \cdot N + f \cdot \partial_{\vec{v}} N$$

$$\therefore d(fN)(\vec{v}_1) \times d(fN)(\vec{v}_2)$$

$$= [\partial_{v_1} f \cdot N + f \cdot \partial_{v_1} N] \times [\partial_{v_2} f \cdot N + f \cdot \partial_{v_2} N]$$

$$\begin{aligned}
&= -f \partial_{v_2} f \cdot N \times \partial_{v_1} N + f \partial_{v_1} f \cdot N \times \partial_{v_2} N + f^2 \partial_{v_1} N \times \partial_{v_2} N \\
\therefore \langle d(fN)(v_1) \times d(fN)(v_2), N \rangle \\
&= f^2 \langle \partial_{v_1} N \times \partial_{v_2} N, N \rangle \quad \text{since } \langle \partial_{v_1} N \times N, N \rangle = 0 \\
\therefore K = \langle \partial_{v_1} N \times \partial_{v_2} N, N \rangle = \frac{1}{f^2} \langle d(fN)(v_1) \times d(fN)(v_2), N \rangle.
\end{aligned}$$

(ii) $\therefore M = h^{-1}(1)$

$\therefore \frac{\nabla h}{|\nabla h|}$ is a normal vector field of M .

$$\begin{aligned}
\therefore |\nabla h| &= \left| \left(\frac{2x}{a^2}, \frac{2y}{b^2}, \frac{2z}{c^2} \right) \right| \\
&= 2 \sqrt{\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4}} = 2f
\end{aligned}$$

$$\therefore fN = f \cdot \frac{\nabla h}{|\nabla h|} = f \cdot \frac{\nabla h}{2f} = \left(\frac{x}{a^2}, \frac{y}{b^2}, \frac{z}{c^2} \right)$$

\therefore if $v = (x_1, y_1, z_1)$, then

$$d(fN)(v) = d\left(\frac{x}{a^2}, \frac{y}{b^2}, \frac{z}{c^2}\right)(v) = \left(\frac{x_1}{a^2}, \frac{y_1}{b^2}, \frac{z_1}{c^2}\right)$$

Let $\{v_1 = (x_1, y_1, z_1), v_2 = (x_2, y_2, z_2)\}$ be an orthonormal basis of TM such that $v_1 \times v_2 = N$

$$\begin{aligned}
\therefore (y_1 z_2 - y_2 z_1, x_2 z_1 - x_1 z_2, x_1 y_2 - x_2 y_1) &= N = \frac{\nabla h}{|\nabla h|} \\
&= \frac{\nabla h}{2f} = \frac{1}{f} \left(\frac{x}{a^2}, \frac{y}{b^2}, \frac{z}{c^2} \right)
\end{aligned}$$

\therefore By (i), $K = \frac{\langle d(fN)(v_1) \times d(fN)(v_2), N \rangle}{f^2}$

$$\begin{aligned}
&= \frac{\left\langle \left(\frac{x_1}{a^2}, \frac{y_1}{b^2}, \frac{z_1}{c^2} \right) \times \left(\frac{x_2}{a^2}, \frac{y_2}{b^2}, \frac{z_2}{c^2} \right), (y_1 z_2 - y_2 z_1, x_2 z_1 - x_1 z_2, x_1 y_2 - x_2 y_1) \right\rangle}{f^2} \\
&= \frac{\frac{(y_1 z_2 - y_2 z_1)^2}{b^2 c^2} + \frac{(x_2 z_1 - x_1 z_2)^2}{a^2 c^2} + \frac{(x_1 y_2 - x_2 y_1)^2}{a^2 b^2}}{f^2} \\
&= \frac{1}{f^2} \left(\frac{1}{b^2 c^2} \cdot \frac{x^2}{f^2 a^4} + \frac{1}{a^2 c^2} \cdot \frac{y^2}{f^2 b^4} + \frac{1}{a^2 b^2} \cdot \frac{z^2}{f^2 c^4} \right) \\
&= \frac{1}{f^4 a^2 b^2 c^2} \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \right) \\
&= \frac{1}{f^4 a^2 b^2 c^2} \quad \text{since } (x, y, z) \text{ lies on } \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1.
\end{aligned}$$